Mapping Features to Automatically Identified Object-Oriented Variability Implementations

The case of ArgoUML-SPL

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Variability-Rich Systems with a Single Code Base



16.000 options managed in 25M LoC [Acher2018]

#ifdef



24.000 different platforms in 2015 [Open2015]

Object-orientation

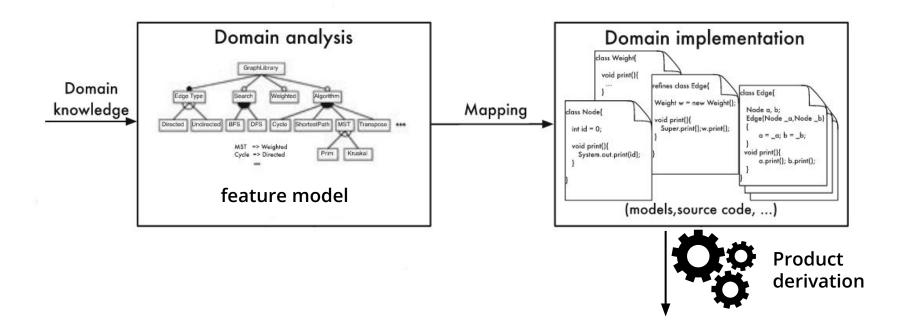


2.000+ options generating variants for platforms, security levels... [Acher2018]

Object-orientation

and many variability implementation techniques...

Problem: How to master them as SPL?



How to engineer an SPL?

Forward-engineering:

Feature model → Domain implementation

Mapping between feature model and features is done **during the implementation**

How to engineer an SPL?

Forward-engineering:

Feature model → Domain implementation

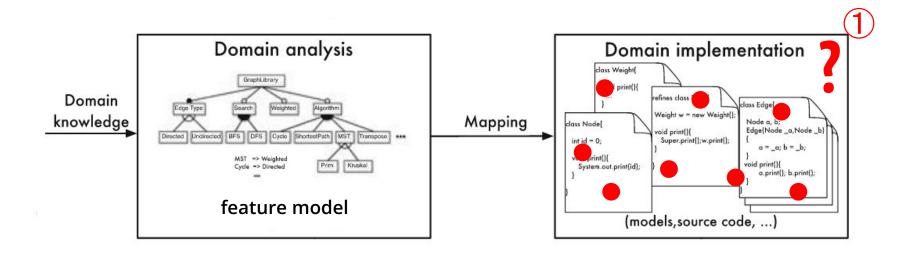
Mapping between feature model and features is done **during the implementation**

Reverse-engineering:

Feature model ← Domain implementation

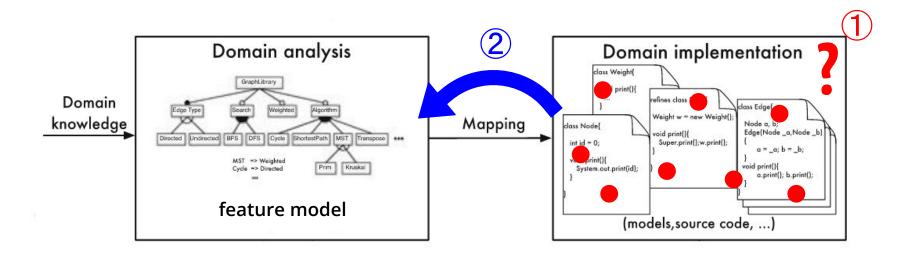
Need to extract the features and build a mapping with the feature model, or build it

Problem 1: How to identify variability implementations in an existing codebase?



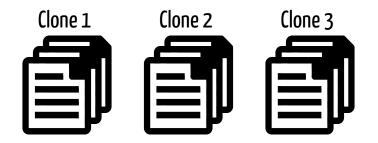
Problem 1: How to identify variability implementations in an existing codebase?

Problem 2: How to map these variability implementations to domain features?



State of the art on variability implementations detection

Context: projects clones

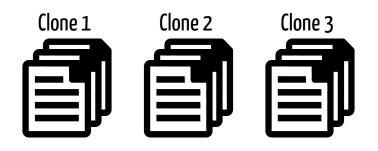


Detection method:

Comparison between clones and mapping with the domain features [Wesley2017]

State of the art on variability implementations detection

Context: projects clones



Detection method:

Comparison between clones and mapping with the domain features [Wesley2017]

Context: unique codebase and

preprocessing directives

#ifdef → variant



<u>Detection method:</u>

Determining the consistency of directives [Liebig2010]

State of the art on variability implementations detection

Our context: large and unique object-oriented codebase

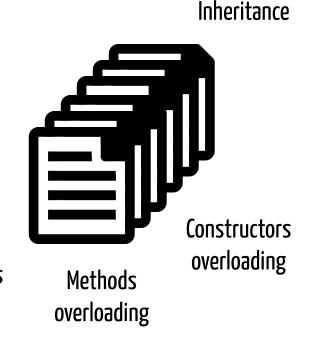
- Several implementation mechanisms
- Variability buried in the code (variation points)

Detection method:

Currently no method

[Lozano2011], [Metzger2014], [Tërnava2017]

Design patterns



Variation points and variants

```
public abstract class Shape {
      public abstract double area();
      public abstract double perimeter(); /*...*/
3
4
    public class Circle extends Shape {
5
      private final double radius;
6
      // Constructor omitted
7
      public double area() {
8
        return Math.PI * Math.pow(radius, 2);
9
10
      public double perimeter() {
11
        return 2 * Math.PI * radius;
12
13
14
```

```
public class Rectangle extends Shape {
15
      private final double width, length;
16
      // Constructor omitted
17
       public double area() {
18
        return width * length;
19
20
      public double perimeter() {
21
        return 2 * (width + length);
23
       public void draw(int x, int y) {
24
      // rectangle at (x, y, width, length)
25
26
       public void draw(Point p) {
      // rectangle at (p.x, p.y, width, length)
29
30
```

Variation points and variants

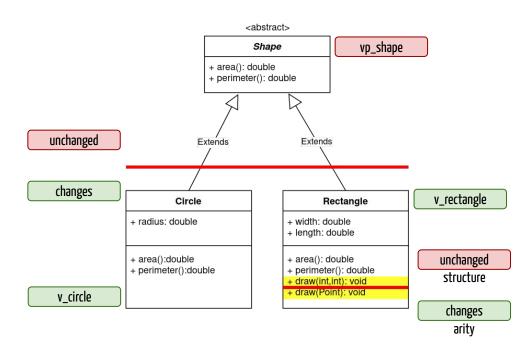
```
vp_shape
    public abstract class Shape {
      public abstract double area();
      public abstract double perimeter(); /*...*/
3
4
                                               v_circle
    public class Circle extends Shape
5
      private final double radius;
6
      // Constructor omitted
7
       public double area() {
8
        return Math.PI * Math.pow(radius, 2);
9
10
      public double perimeter() {
11
        return 2 * Math.PI * radius;
12
13
14
```

```
v_rectangle
    public class Rectangle extends Shape {
15
       private final double width, length;
16
       // Constructor omitted
17
       public double area() {
18
        return width * length;
19
20
      public double perimeter() {
21
         return 2 * (width + length);
                                              vp_draw
23
      public void draw(int x, int y) {
24
      // rectangle at (x, y, width, length)
      public void draw(Point p) {
       // rectangle at (p.x, p.y, width, length)
29
30
```

Use of symmetries to detect variability implementations?

Intuition:

- Presence of **symmetries in object-oriented codebases** [Coplien2019] inspired from the theory of centres [Alexander2002]
- Symmetries present in mechanisms implementing variability



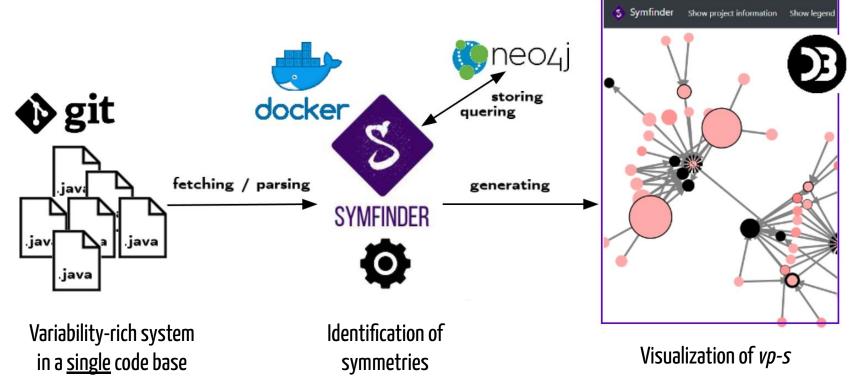
Identifying variation points with variants

Variability implementation technique
 → local symmetry
 - variation point (commonality)
 → unchanged
 - variant (variability)
 → changes

Identification through local symmetries in core assets

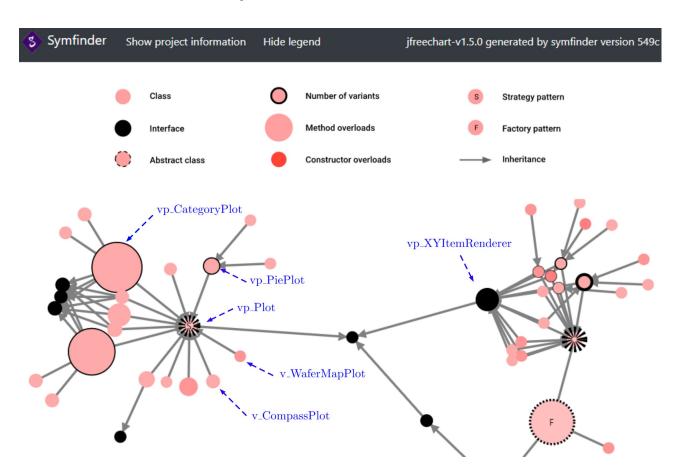
High density of symmetries → variability intense places

symfinder

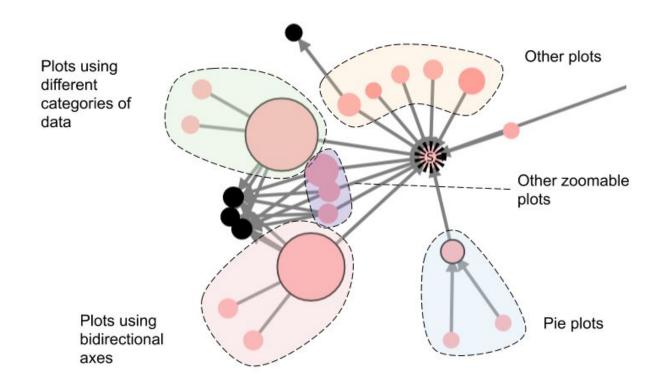


Xhevahire Tërnava, Johann Mortara, and Philippe Collet. 2019. Identifying and Visualizing Variability in Object-Oriented Variability-Rich Systems. In 23rd International Systems and Software Product Line Conference - Volume A (SPLC '19), September 9–13, 2019, Paris, France. ACM, New York, NY, USA, 12 pages.

Automatic visualization of *vp-s* with variants

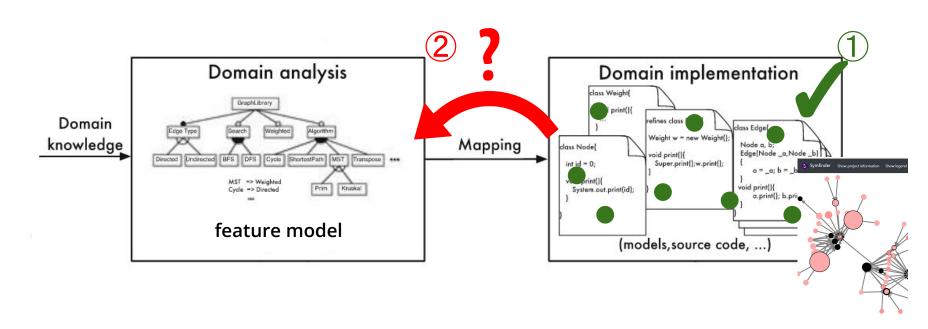


What can be manually found: an example

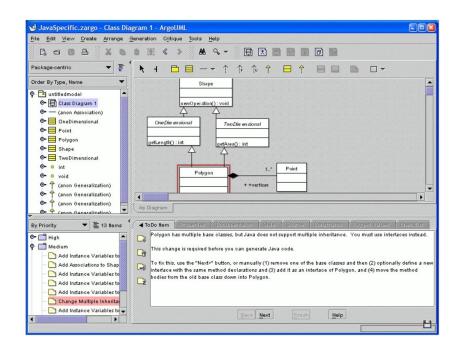


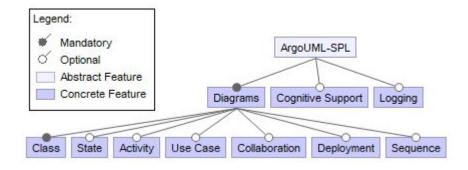
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ArgoUML-SPL [Couto2011]

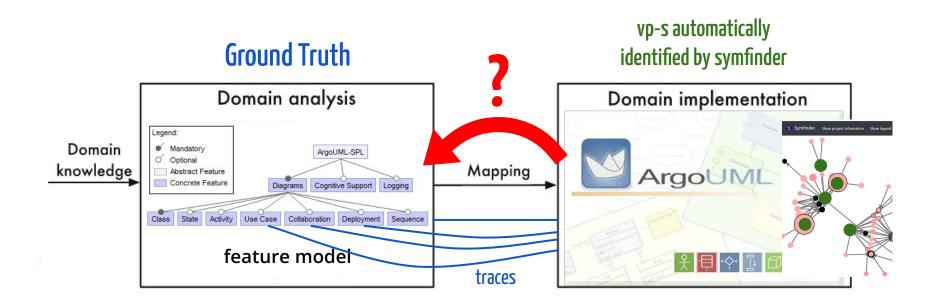




Feature model of ArgoUML-SPL

ArgoUML editor

Question: Are the identified *vp-s* from ArgoUML relevant for a feature mapping?



Experimental setup

Ground Truth

Excerpt of traces for USECASE feature

org.argouml.uml.diagram.use_case.ui.FigActor

```
//#if defined(USECASEDIAGRAM)
//@#$LPS-USECASEDIAGRAM:GranularityType:Package
public class FigActor extends FigNodeModelElement
```

org.argouml.uml.diagram.use_case.ui.FigClassifierRole

```
//#if defined(SEQUENCEDIAGRAM)
//@#$LPS-SEQUENCEDIAGRAM:GranularityType:Package
public class FigClassifierRole extends FigNodeModelElement
```

Experimental setup

Ground Truth

Excerpt of traces for USECASE feature

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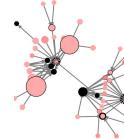
```
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public class FigActor extends FigNodeModelElement
```

 $\verb|org.argouml.uml.diagram.use_case.ui.FigClassifierRole|\\$

```
//#if defined(SEQUENCEDIAGRAM)
//@#$LPS-SEQUENCEDIAGRAM:GranularityType:Package
public class FigClassifierRole extends FigNodeModelElement
```

.

Excerpt of *symfinder* JSON output



```
"nodes": [
     "types": [
        "CLASS", "METHOD LEVEL VP", "VARIANT"
     "constructorVPs": 1,
      "methodVariants": 0,
      "classVariants": 0,
     "methodVPs": 0,
     "constructorVariants": 3,
      "name":
"org.argouml.uml.diagram.use case.ui.FigActor"
 "links": [
     "type": "EXTENDS",
      "source":
"org.argouml.uml.diagram.ui.FigNodeModelElement",
      "target":
"org.argouml.uml.diagram.use case.ui.FigActor"
                                                  22
```

Experimental setup

Ground Truth

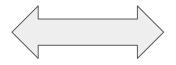
Excerpt of traces for USECASE feature

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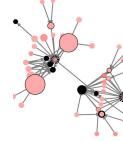
 $\verb"org.argouml.uml.diagram.use_case.ui.FigClassifierRole"$

//#if defined(SEQUENCEDIAGRAM)
//@#\$LPS-SEQUENCEDIAGRAM:GranularityType:Package
public class FigClassifierRole extends FigNodeModelElement



Manual mapping using Excel formulae

Excerpt of *symfinder* JSON output



```
"nodes": [
      "types": [
        "CLASS", "METHOD LEVEL VP", "VARIANT"
     "constructorVPs": 1,
      "methodVariants": 0,
      "classVariants": 0,
      "methodVPs": 0,
      "constructorVariants": 3,
      "name":
"org.argouml.uml.diagram.use case.ui.FigActor"
 "links": [
     "type": "EXTENDS",
      "source":
"org.argouml.uml.diagram.ui.FigNodeModelElement",
      "target":
"org.argouml.uml.diagram.use case.ui.FigActor"
```

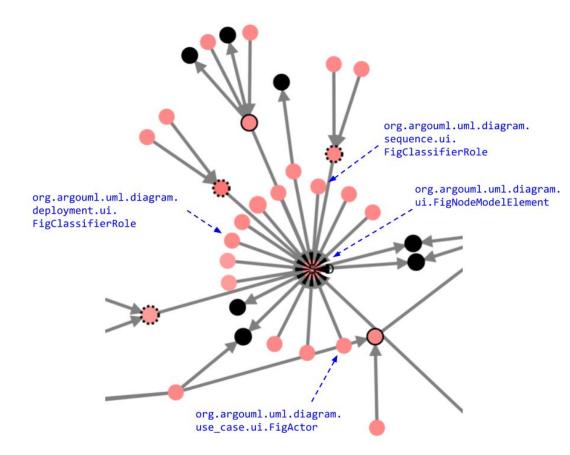
Validation

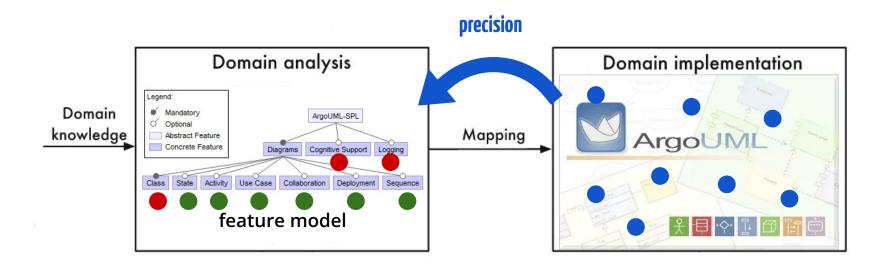
Feature: Use Case

//#if defined(USECASEDIAGRAM)
//@#\$LPS-USECASEDIAGRAM:GranularityType:Package
public class FigActor extends FigNodeModelElement

Feature: Sequence

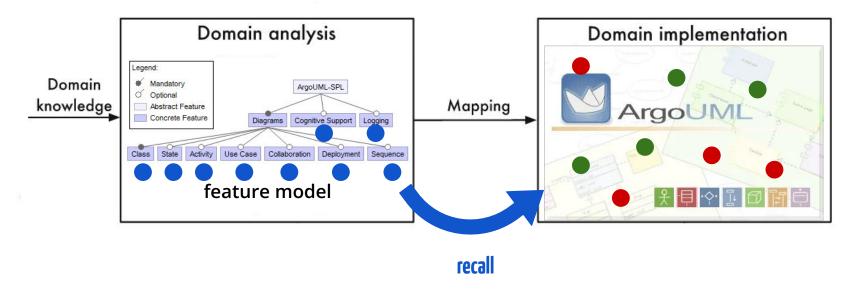
//#if defined(SEQUENCEDIAGRAM)
//@#\$LPS-SEQUENCEDIAGRAM:GranularityType:Package
public class FigClassifierRole extends FigNodeModelElement





Precision:

Percentage of identified vp-s and variants that could be mapped to domain features



Recall:

Percentage of features' traces that could be mapped to identified vp-s and variants

Calculating precision

$$precision = \frac{TP}{TP + FP} = \frac{|T_{gt} \cap I_{vp-v}|}{|I_{vp-v}|} = \frac{593}{1560} = 38\%$$

Low precision was expected:

- coarse grain features based on superficial domain knowledge
- not all identified places with a symmetry are related to variability

Calculating recall

$$recall = \frac{TP}{TP + FN} = \frac{|T_{gt} \cap I_{vp-v}|}{|T_{gt}|} = \frac{593}{712} = 83\%$$

The missing 17% of traces are **not variability related**:

- initialization classes
- external libraries

Future work

Map the identified *vp-s* with variants to #ifdef directives

Take into account *vp-s* with variants at method level

Extend symfinder to be able to analyse projects in other languages



Mapping Features to Automatically Identified Object-Oriented Variability Implementations

The case of ArgoUML-SPL

Successful mapping to preexisting domain features

vp-s detection method islittle precise but highlyrobust on ArgoUML-SPL

symfinder identifies *vp-s*with variants relevant for feature mapping

Availability:

- Public release: tag vamos2020
 https://github.com/DeathStar3/symfinder
- symfinder demonstration
 https://deathstar3.github.io/symfinder-demo/

Get the paper:



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